Architecture of FPGAs and CPLDs: A Tutorial

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Abstract

This paper provides a tutorial survey of architectures of commercially available high-capacity field-programmable devices (FPDs). We first define the relevant terminology in the field and then describe the recent evolution of FPDs. The three main categories of FPDs are delineated: Simple PLDs (SPLDs), Complex PLDs (CPLDs) and Field-Programmable Gate Arrays (FPGAs). We then give details of the architectures of all of the most important commercially available chips, and give examples of applications of each type of device.
1 Introduction to High-Capacity FPDs

Prompted by the development of new types of sophisticated field-programmable devices (FPDs), the process of designing digital hardware has changed dramatically over the past few years. Unlike previous generations of technology, in which board-level designs included large numbers of SSI chips containing basic gates, virtually every digital design produced today consists mostly of high-density devices. This applies not only to custom devices like processors and memory, but also for logic circuits such as state machine controllers, counters, registers, and decoders. When such circuits are destined for high-volume systems they have been integrated into high-density gate arrays. However, gate array NRE costs often are too expensive and gate arrays take too long to manufacture to be viable for prototyping or other low-volume scenarios. For these reasons, most prototypes, and also many production designs are now built using FPDs. The most compelling advantages of FPDs are instant manufacturing turnaround, low start-up costs, low financial risk and (since programming is done by the end user) ease of design changes.

The market for FPDs has grown dramatically over the past decade to the point where there is now a wide assortment of devices to choose from. A designer today faces a daunting task to research the different types of chips, understand what they can best be used for, choose a particular manufacturers’s product, learn the intricacies of vendor-specific software and then design the hardware. Confusion for designers is exacerbated by not only the sheer number of FPDs available, but also by the complexity of the more sophisticated devices. The purpose of this paper is to provide an overview of the architecture of the various types of FPDs. The emphasis is on devices with relatively high logic capacity; all of the most important commercial products are discussed.

Before proceeding, we provide definitions of the terminology in this field. This is necessary because the technical jargon has become somewhat inconsistent over the past few years as companies have attempted to compare and contrast their products in literature.
1.1 Definitions of Relevant Terminology

The most important terminology used in this paper is defined below.

- **Field-Programmable Device (FPD)** — a general term that refers to any type of integrated circuit used for implementing digital hardware, where the chip can be configured by the end user to realize different designs. Programming of such a device often involves placing the chip into a special programming unit, but some chips can also be configured “in-system”. Another name for FPDs is *programmable logic devices* (PLDs); although PLDs encompass the same types of chips as FPDs, we prefer the term FPD because historically the word PLD has referred to relatively simple types of devices.

- **PLA** — a Programmable Logic Array (PLA) is a relatively small FPD that contains two levels of logic, an AND-plane and an OR-plane, where both levels are programmable (note: although PLA structures are sometimes embedded into full-custom chips, we refer here only to those PLAs that are provided as separate integrated circuits and are user-programmable).

- **PAL** — a Programmable Array Logic (PAL) is a relatively small FPD that has a programmable AND-plane followed by a fixed OR-plane

- **SPLD** — refers to any type of Simple PLD, usually either a PLA or PAL

- **CPLD** — a more Complex PLD that consists of an arrangement of multiple SPLD-like blocks on a single chip. Alternative names (that will not be used in this paper) sometimes adopted for this style of chip are Enhanced PLD (EPLD), Super PAL, Mega PAL, and others.

- **FPGA** — a Field-Programmable Gate Array is an FPD featuring a general structure that allows very high logic capacity. Whereas CPLDs feature logic resources with a wide number of inputs (AND planes), FPGAs offer more narrow logic resources. FPGAs also offer a higher ratio of flip-flops to logic resources than do CPLDs.

- **HCPLDs** — high-capacity PLDs: a single acronym that refers to both CPLDs and FPGAs. This term has been coined in trade literature for providing an easy way to refer to both types of devices. We do not use this term in the paper.

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* PAL is a trademark of Advanced Micro Devices.
• **Interconnect** — the wiring resources in an FPD.

• **Programmable Switch** — a user-programmable switch that can connect a logic element to an interconnect wire, or one interconnect wire to another.

• **Logic Block** — a relatively small circuit block that is replicated in an array in an FPD. When a circuit is implemented in an FPD, it is first decomposed into smaller sub-circuits that can each be mapped into a logic block. The term logic block is mostly used in the context of FPGAs, but it could also refer to a block of circuitry in a CPLD.

• **Logic Capacity** — the amount of digital logic that can be mapped into a single FPD. This is usually measured in units of “equivalent number of gates in a traditional gate array”. In other words, the capacity of an FPD is measured by the size of gate array that it is comparable to. In simpler terms, logic capacity can be thought of as “number of 2-input NAND gates”.

• **Logic Density** — the amount of logic per unit area in an FPD.

• **Speed-Performance** — measures the maximum operable speed of a circuit when implemented in an FPD. For combinational circuits, it is set by the longest delay through any path, and for sequential circuits it is the maximum clock frequency for which the circuit functions properly.

In the remainder of this section, to provide insight into FPD development the evolution of FPDs over the past two decades is described. Additional background information is also included on the semiconductor technologies used in the manufacture of FPDs.

### 1.2 Evolution of Programmable Logic Devices

The first type of user-programmable chip that could implement logic circuits was the Programmable Read-Only Memory (PROM), in which address lines can be used as logic circuit inputs and data lines as outputs. Logic functions, however, rarely require more than a few product terms, and a PROM contains a full decoder for its address inputs. PROMs are thus an inefficient architecture for realizing logic circuits, and so are rarely used in practice for that purpose. The first device developed later specifically for implementing logic circuits was the Field-Programmable Logic Array (FPLA), or simply PLA for short. A PLA consists of two levels of logic gates: a program-
mable “wired” AND-plane followed by a programmable “wired” OR-plane. A PLA is structured so that any of its inputs (or their complements) can be AND’ed together in the AND-plane; each AND-plane output can thus correspond to any product term of the inputs. Similarly, each OR-plane output can be configured to produce the logical sum of any of the AND-plane outputs. With this structure, PLAs are well-suited for implementing logic functions in sum-of-products form. They are also quite versatile, since both the AND terms and OR terms can have many inputs (this feature is often referred to as wide AND and OR gates).

When PLAs were introduced in the early 1970s, by Philips, their main drawbacks were that they were expensive to manufacture and offered somewhat poor speed-performance. Both disadvantages were due to the two levels of configurable logic, because programmable logic planes were difficult to manufacture and introduced significant propagation delays. To overcome these weaknesses, Programmable Array Logic (PAL) devices were developed. As Figure 1 illustrates, PALs feature only a single level of programmability, consisting of a programmable “wired” AND-plane that feeds fixed OR-gates. To compensate for lack of generality incurred because the OR-
plane is fixed, several variants of PALs are produced, with different numbers of inputs and outputs, and various sizes of OR-gates. PALs usually contain flip-flops connected to the OR-gate outputs so that sequential circuits can be realized. PAL devices are important because when introduced they had a profound effect on digital hardware design, and also they are the basis for some of the newer, more sophisticated architectures that will be described shortly. Variants of the basic PAL architecture are featured in several other products known by different acronyms. All small PLDs, including PLAs, PALs, and PAL-like devices are grouped into a single category called Simple PLDs (SPLDs), whose most important characteristics are low cost and very high pin-to-pin speed-performance.

As technology has advanced, it has become possible to produce devices with higher capacity than SPLDs. The difficulty with increasing capacity of a strict SPLD architecture is that the structure of the programmable logic-planes grow too quickly in size as the number of inputs is increased. The only feasible way to provide large capacity devices based on SPLD architectures is then to integrate multiple SPLDs onto a single chip and provide interconnect to programmably connect the SPLD blocks together. Many commercial FPD products exist on the market today with this basic structure, and are collectively referred to as Complex PLDs (CPLDs).

CPLDs were pioneered by Altera, first in their family of chips called Classic EPLDs, and then in three additional series, called MAX 5000, MAX 7000 and MAX 9000. Because of a rapidly growing market for large FPDs, other manufacturers developed devices in the CPLD category and there are now many choices available. All of the most important commercial products will be described in Section 2. CPLDs provide logic capacity up to the equivalent of about 50 typical SPLD devices, but it is somewhat difficult to extend these architectures to higher densities. To build FPDs with very high logic capacity, a different approach is needed.
The highest capacity general purpose logic chips available today are the traditional gate arrays sometimes referred to as *Mask-Programmable Gate Arrays* (MPGAs). MPGAs consist of an array of pre-fabricated transistors that can be customized into the user’s logic circuit by connecting the transistors with custom wires. Customization is performed during chip fabrication by specifying the metal interconnect, and this means that in order for a user to employ an MPGA a large setup cost is involved and manufacturing time is long. Although MPGAs are clearly not FPDs, they are mentioned here because they motivated the design of the user-programmable equivalent: Field-Programmable Gate Arrays (FPGAs). Like MPGAs, FPGAs comprise an array of uncommitted circuit elements, called *logic blocks*, and interconnect resources, but FPGA configuration is performed through programming by the end user. An illustration of a typical FPGA architecture appears in Figure 2. As the only type of FPD that supports very high logic capacity, FPGAs have been responsible for a major shift in the way digital circuits are designed.

Figure 2 - *Structure of an FPGA.*
Figure 3 summarizes the categories of FPDs by listing the logic capacities available in each of the three categories. In the figure, “equivalent gates” refers loosely to “number of 2-input NAND gates”. The chart serves as a guide for selecting a specific device for a given application, depending on the logic capacity needed. However, as we will discuss shortly, each type of FPD is inherently better suited for some applications than for others. It should also be mentioned that there exist other special-purpose devices optimized for specific applications (e.g. state machines, analog gate arrays, large interconnection problems). However, since use of such devices is limited they will not be described here. The next sub-section discusses the methods used to implement the user-programmable switches that are the key to the user-customization of FPDs.

1.3 User-Programmable Switch Technologies

The first type of user-programmable switch developed was the fuse used in PLAs. Although fuses are still used in some smaller devices, we will not discuss them here because they are quickly being replaced by newer technology. For higher density devices, where CMOS dominates the IC industry, different approaches to implementing programmable switches have been developed. For CPLDs the main switch technologies (in commercial products) are floating gate transistors like

![Figure 3 - FPD Categories by Logic Capacity.](image-url)
those used in EPROM and EEPROM, and for FPGAs they are SRAM and antifuse. Each of these is briefly discussed below.

An EEPROM or EPROM transistor is used as a programmable switch for CPLDs (and also for many SPLDs) by placing the transistor between two wires in a way that facilitates implementation of wired-AND functions. This is illustrated in Figure 4, which shows EPROM transistors as they might be connected in an AND-plane of a CPLD. An input to the AND-plane can drive a product wire to logic level ‘0’ through an EPROM transistor, if that input is part of the corresponding product term. For inputs that are not involved for a product term, the appropriate EPROM transistors are programmed to be permanently turned off. A diagram for an EEPROM-based device would look similar.

Although there is no technical reason why EPROM or EEPROM could not be applied to FPGAs, current commercial FPGA products are based either on SRAM or antifuse technologies, as discussed below.

An example of usage of SRAM-controlled switches is illustrated in Figure 5, showing two applications of SRAM cells: for controlling the gate nodes of pass-transistor switches and to con-

![Figure 4 - EPROM Programmable Switches.](image-url)
trol the select lines of multiplexers that drive logic block inputs. The figures gives an example of the connection of one logic block (represented by the AND-gate in the upper left corner) to another through two pass-transistor switches, and then a multiplexer, all controlled by SRAM cells. Whether an FPGA uses pass-transistors or multiplexers or both depends on the particular product.

The other type of programmable switch used in FPGAs is the antifuse. Antifuses are originally open-circuits and take on low resistance only when programmed. Antifuses are suitable for FPGAs because they can be built using modified CMOS technology. As an example, Actel’s antifuse structure, known as PLICE [Ham88], is depicted in Figure 6. The figure shows that an antifuse is positioned between two interconnect wires and physically consists of three sandwiched layers: the top and bottom layers are conductors, and the middle layer is an insulator. When unprogrammed, the insulator isolates the top and bottom layers, but when programmed the insulator changes to become a low-resistance link. PLICE uses Poly-Si and n+ diffusion as conductors.

Figure 5 - SRAM-controlled Programmable Switches.
and ONO (see [Ham88]) as an insulator, but other antifuses rely on metal for conductors, with amorphous silicon as the middle layer [Birk92][Marp94].

Table 1 lists the most important characteristics of the programming technologies discussed in this section. The left-most column of the table indicates whether the programmable switches are one-time programmable (OTP), or can be re-programmed (RP). The next column lists whether the switches are volatile, and the last column names the underlying transistor technology.

<table>
<thead>
<tr>
<th>Name</th>
<th>Re-programmable</th>
<th>Volatile</th>
<th>Technology</th>
</tr>
</thead>
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<tr>
<td>Fuse</td>
<td>no</td>
<td>no</td>
<td>Bipolar</td>
</tr>
<tr>
<td>EPROM</td>
<td>yes out of circuit</td>
<td>no</td>
<td>UVCMOS</td>
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<tr>
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<td>yes in circuit</td>
<td>no</td>
<td>EECMOS</td>
</tr>
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<td>yes in circuit</td>
<td>yes</td>
<td>CMOS</td>
</tr>
<tr>
<td>Antifuse</td>
<td>no</td>
<td>no</td>
<td>CMOS+</td>
</tr>
</tbody>
</table>

Table 1 - Summary of Programming Technologies.

Figure 6 - Actel Antifuse Structure.
1.4 Computer Aided Design (CAD) Flow for FPDs

When designing circuits for implementation in FPDs, it is essential to employ Computer-Aided Design (CAD) programs. Such software tools are discussed briefly in this section to provide a feel for the design process involved.

CAD tools are important not only for complex devices like CPLDs and FPGAs, but also for SPLDs. A typical CAD system for SPLDs would include software for the following tasks: initial design entry, logic optimization, device fitting, simulation, and configuration. This design flow is illustrated in Figure 7, which also indicates how some stages feed back to others. Design entry may be done either by creating a schematic diagram with a graphical CAD tool, by using a text-based system to describe a design in a simple hardware description language, or with a mixture of design entry methods. Since initial logic entry is not usually in an optimized form, algorithms are employed to optimize the circuits, after which additional algorithms analyse the resulting logic equations and “fit” them into the SPLD. Simulation is used to verify correct operation, and the user would return to the design entry step to fix errors. When a design simulates correctly it can be loaded into a programming unit and used to configure an SPLD. One final detail to note about Figure 7 is that while the original design entry step is performed manually by the designer, all other steps are carried out automatically by most CAD systems.

Figure 7 - CAD Design Flow for SPLDs.
The steps involved for implementing circuits in CPLDs are similar to those for SPLDs, but the tools themselves are more sophisticated. Because the devices are complex and can accommodate large designs, it is more common to use a mixture of design entry methods for different modules of a complete circuit. For instance, some modules might be designed with a small hardware description language like ABEL, others drawn using a symbolic schematic capture tool, and still others described via a full-featured hardware description language such as VHDL. Also, for CPLDs the process of “fitting” a design may require steps similar to those described below for FPGAs, depending on how sophisticated the CPLD is. The necessary software for these tasks is supplied either by the CPLD manufacturer or a third party.

The design process for FPGAs is similar to that for CPLDs, but additional tools are needed to support the increased complexity of the chips. The major difference is in the “device fitter” step that comes after logic optimization and before simulation, where FPGAs require at least three steps: a technology mapper to map from basic logic gates into the FPGA’s logic blocks, placement to choose which specific logic blocks to use in the FPGA, and a router to allocate the wire segments in the FPGA to interconnect the logic blocks. With this added complexity, the CAD tools might require a fairly long period of time (often more than an hour or even several hours) to complete their tasks.

2 Overview of Commercially Available FPDs

This section provides many examples of commercial FPD products. SPLDs are first discussed briefly, and then details are given for all of the most important CPLDs and FPGAs. The reader who is interested in more details on the commercial products is encouraged to contact the manufacturers, or their distributors, for the latest data sheets*.

* Most FPD manufacturers now provide their data sheets on the world wide web, and can be located at URL “http://www.companyname.com”.
2.1 Commercially Available SPLDs

As the staple for digital hardware designers for the past two decades, SPLDs are very important devices. SPLDs represent the highest speed-performance FPDs available, and are inexpensive. However, they are also fairly straight-forward and well understood, so this paper will discuss them only briefly.

Two of the most popular SPLDs are the PALs produced by Advanced Micro Devices (AMD) known as the 16R8 and 22V10. Both of these devices are industry standards and are widely second-sourced by various companies. The name “16R8” means that the PAL has a maximum of 16 inputs (there are 8 dedicated inputs and 8 input/outputs), and a maximum of 8 outputs. The “R” refers to the type of outputs provided by the PAL and means that each output is “registered” by a D flip-flop. Similarly, the “22V10” has a maximum of 22 inputs and 10 outputs. Here, the “V” means each output is “versatile” and can be configured in various ways, some configurations registered and some not.

Another widely used and second sourced SPLD is the Altera Classic EP610. This device is similar in complexity to PALs, but it offers more flexibility in the way that outputs are produced and has larger AND- and OR- planes. In the EP610, outputs can be registered and the flip-flops are configurable as any of D, T, JK, or SR.

In addition to the SPLDs mentioned above many other products are available from a wide array of companies. All SPLDs share common characteristics, like some sort of logic planes (AND, OR, NOR, or NAND), but each specific product offers unique features that may be particularly attractive for some applications. A partial list of companies that offer SPLDs includes: AMD, Altera, ICT, Lattice, Cypress, and Philips-Signetics. Since some of these SPLDs have complexity approaching that found in CPLDs, the paper will now move on to more sophisticated devices.
2.2 Commercially Available CPLDs

As stated earlier, CPLDs consist of multiple SPLD-like blocks on a single chip. However, CPLD products are much more sophisticated than SPLDs, even at the level of their basic SPLD-like blocks. In this section, CPLDs are discussed in detail, first by surveying the available commercial products and then by discussing the types of applications for which CPLDs are best suited. Sufficient details are presented to allow a comparison between the various competing products, with more attention being paid to devices that we believe are in more widespread use than others.

2.2.1 Altera CPLDs

Altera has developed three families of chips that fit within the CPLD category: MAX 5000, MAX 7000, and MAX 9000. Here, the discussion will focus on the MAX 7000 series, because it is widely used and offers state-of-the-art logic capacity and speed-performance. MAX 5000 represents an older technology that offers a cost effective solution, and MAX 9000 is similar to MAX 7000, except that MAX 9000 offers higher logic capacity (the industry’s highest for CPLDs).

The general architecture of the Altera MAX 7000 series is depicted in Figure 8. It comprises an array of blocks called Logic Array Blocks (LABs), and interconnect wires called a Program-
mable Interconnect Array (PIA). The PIA is capable of connecting any LAB input or output to any other LAB. Also, the inputs and outputs of the chip connect directly to the PIA and to LABs. A LAB can be thought of as a complex SPLD-like structure, and so the entire chip can be considered to be an array of SPLDs. MAX 7000 devices are available both based in EPROM and EEPROM technology. Until recently, even with EEPROM, MAX 7000 chips could be programmable only “out-of-circuit” in a special-purpose programming unit; however, in 1996 Altera released the 7000S series, which is reprogrammable “in-circuit”.

The structure of a LAB is shown in Figure 9. Each LAB consists of two sets of eight macrocells (shown in Figure 10), where a macrocell comprises a set of programmable product terms (part of an AND-plane) that feeds an OR-gate and a flip-flop. The flip-flops can be configured as D type, JK, T, SR, or can be transparent. As illustrated in Figure 10, the number of inputs to the

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**Figure 9 - Altera MAX 7000 Logic Array Block (LAB).**

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OR-gate in a macrocell is variable; the OR-gate can be fed from any or all of the five product terms within the macrocell, and in addition can have up to 15 extra product terms from macrocells in the same LAB. This product term flexibility makes the MAX 7000 series LAB more efficient in terms of chip area because typical logic functions do not need more than five product terms, and the architecture supports wider functions when they are needed. It is interesting to note that variable sized OR-gates of this sort are not available in basic SPLDs (see Figure 1). Similar features of this kind are found in other CPLD architectures discussed shortly.

Besides Altera, several other companies produce devices that can be categorized as CPLDs. For example, AMD manufacturers the Mach family, Lattice has the (i)pLSI series, Xilinx produces a CPLD series that they call XC7000 (unrelated to the Altera MAX 7000 series) and has announced a new family called XC9500, and ICT has the PEEL array. These devices are discussed in the following sub-sections.

Figure 10 - MAX 7000 Macrocell.
2.2.2 Advanced Micro Devices (AMD) CPLDs

AMD offers a CPLD family with five sub-families called Mach 1 to Mach 5. Each Mach device comprises multiple PAL-like blocks: Mach 1 and 2 consist of optimized 22V16 PALs, and Mach 3 and 4 comprise several optimized 34V16 PALs, and Mach 5 is similar but offers enhanced speed-performance. All Mach chips are based on EEPROM technology, and together the five sub-families provide a wide range of selection, from small, inexpensive chips to larger state-of-the-art ones. This discussion will focus on Mach 4, because it represents the most advanced currently available parts in the Mach family.

Figure 11 depicts a Mach 4 chip, showing the multiple 34V16 PAL-like blocks, and the interconnect, called Central Switch Matrix, for connecting the blocks together. Chips range in size from 6 to 16 PAL blocks, which corresponds roughly to 2000 to 5000 equivalent gates and are in-circuit programmable. All connections in Mach 4 between one PAL block and another (even from a PAL block to itself) are routed through the Central Switch Matrix. The device can thus be
viewed not only as a collection of PALs, but also as a single large device. Since all connections travel through the same path, timing delays of circuits implemented in Mach 4 are predictable.

A Mach 4 PAL-like block is depicted in Figure 12. It has 16 outputs and a total of 34 inputs (16 of which are the outputs fed-back), so it corresponds to a 34V16 PAL. However, there are two key differences between this block and a normal PAL: 1. there is a product term allocator between the AND-plane and the macrocells (the macrocells comprise an OR-gate, an EX-OR gate and a flip-flop), and 2. there is an output switch matrix between the OR-gates and the I/O pins. These two features make a Mach 4 chip easier to use, because they “decouple” sections of the PAL block. More specifically, the product term allocator distributes and shares product terms from the AND-plane to whichever OR-gates require them. This is much more flexible than the fixed-size OR-gates in regular PALs. The output switch matrix makes it possible for any macrocell output (OR-gate or flip-flop) to drive any of the I/O pins connected to the PAL block. Again, flexibility is enhanced over a PAL, where each macrocell can drive only one specific I/O pin. Mach 4’s combination of in-system programmability and high flexibility promote easy hardware design changes.

![Figure 12 - AMD Mach 4 PAL-like (34V16) Block.](image-url)
2.2.3 Lattice CPLDs

Lattice offers a complete range of CPLDs, with two main product lines: the Lattice pLSI consist of three families of EEPROM CPLDs, and the ispLSI are the same as the pLSI devices, except that they are in-system programmable. For both the pLSI and ispLSI products, Lattice offers three families that have different logic capacities and speed-performance.

Lattice’s earliest generation of CPLDs is the pLSI and ispLSI 1000 series. Each chip consists of a collection of SPLD-like blocks, described in more detail later, and a global routing pool to connect blocks together. Logic capacity ranges from about 1200 to 4000 gates. Pin-to-pin delays are 10 nsec. Lattice also offers a CPLD family called the 2000 series, which are relatively small CPLDs, with between 600 and 2000 gates that offer a higher ratio of macrocells to I/O pins and higher speed-performance than the 1000 series. At 5.5 nsec pin-to-pin delays, the 2000 series offers state-of-the-art speed.

Lattice’s 3000 series represents their largest CPLDs, with up to 5000 gates. Pin-to-pin delays for this device are about 10-15 nsec. In terms of other chips discussed so far, the 3000 series functionality is most similar to AMD’s Mach 4. The 3000 series offers some enhancements over the other Lattice parts to support more recent design styles, such as JTAG boundary scan.

The general structure of a Lattice pLSI or ispLSI device is indicated in Figure 13. Around the outside edges of the chip are the bi-directional I/Os, which are connected both to the Generic Logic Blocks (GLBs) and the Global Routing Pool (GRP). As the fly-out on the right side of the figure shows, the GLBs are small PAL-like blocks that consist of an AND-plane, product term allocator, and macrocells. The GRP is a set of wires that span the entire chip and are available to connect the GLB inputs and outputs together. All interconnections pass through the GRP, so timing between levels of logic in the Lattice chips is fully predictable, much as it is for the AMD Mach devices.
2.2.4 Cypress FLASH370 CPLDs

Cypress has recently developed a family of CPLD products that are similar to both the AMD and Lattice devices in several ways. The Cypress CPLDs, called FLASH370 are based on FLASH EEPROM technology, and offer speed-performance of 8.5 to 15 nsec pin-to-pin delays. The FLASH370 parts are not in-system programmable. Recognizing that larger chips need more I/Os, FLASH370 provides more I/Os than competing products, featuring a linear relationship between the number of macrocells and number of bi-directional I/O pins. The smallest parts have 32 macrocells and 32 I/Os and the largest 256 macrocells and 256 I/Os.

Figure 14 shows that FLASH370 has a typical CPLD architecture with multiple PAL-like blocks and a programmable interconnect matrix (PIM) to connect them. Within each PAL-like block, there is an AND-plane that feeds a product term allocator that directs from 0 to 16 product terms to each of 32 OR-gates. Note that in the feed-back path from the macrocell outputs to the
PIM, there are 32 wires; this means that a macrocell can be buried (not drive an I/O pin) and yet the I/O pin that could be driven by the macrocell can still be used as an input. This illustrates another type of flexibility available in PAL-like blocks in CPLDs, but not present in normal PALs.

2.2.5 Xilinx XC7000 CPLDs

Although Xilinx is mostly a manufacturer of FPGAs, they also offer a selection of CPLDs, called XC7000, and have announced a new CPLD family called XC9500. There are two main families in the XC7000 offering: the 7200 series, originally marketed by Plus Logic as the Hiper EPLDs, and the 7300 series, developed by Xilinx. The 7200 series are moderately small devices, with about 600 to 1500 gates capacity, and they offer speed-performance of about 25 nsec pin-to-pin delays. Each chip consists of a collection of SPLD-like blocks that each have 9 macrocells. The macrocells in the 7200 series are different from those in other CPLDs in that each macrocell includes two OR-gates and each of these OR-gates is input to a two-bit Arithmetic Logic Unit (ALU). The ALU can produce any functions of its two inputs, and its output feeds a configurable flip-flop. The Xilinx 7300 series is an enhanced version of the 7200, offering more capacity (up to 3000 gates when the entire family becomes available) and higher speed-performance. Finally, the
new XC9500, when available, will offer in-circuit programmability with 5 nsec pin-to-pin delays and up to 6200 logic gates.

2.2.6 Altera FLASHlogic CPLDs

Altera’s FLASHlogic, previously known as Intel’s FLEXlogic, features in-system programmability and provides on-chip SRAM blocks, a unique feature among CPLD products. The upper part of Figure 15 illustrates the architecture of FLASHlogic devices; it comprises a collection of PAL-like blocks, called Configurable Function Blocks (CFBs), that each represents an optimized 24V10 PAL.

![Figure 15 - Altera FLASHlogic CPLD.](image_url)
In terms of basic structure, FLASHlogic is similar to other products already discussed. However, they have one unique feature that stands them apart from all other CPLDs: each PAL-like block, instead of being used for AND-OR logic, can be configured as a block of 10 nsec Static RAM. This concept is illustrated in the lower part of Figure 15, which shows one CFB being used as a PAL and another configured as an SRAM. In the SRAM configuration, the PAL block becomes a 128 word by 10 bit read/write memory. Inputs that would normally feed the AND-plane in the PAL in this case become address lines, data in, and control signals for the memory. Notice that the flip-flops and tri-state buffers are still available when the PAL block is configured as memory.

In the FLASHlogic device, the AND-OR logic plane’s configuration bits are SRAM cells that are “shadowed” by EPROM or EEPROM cells. The SRAM cells are loaded with a copy of the non-volatile EPROM or EEPROM memory when power is applied, but it is the SRAM cells that control the configuration of the chip. It is possible to re-configure the chips in-system by downloading new information into the SRAM cells. The SRAM cells’ contents can be written back to the EEPROM, so that non-volatile re-programming (in-circuit) is available.

2.2.7 ICT PEEL Arrays

The ICT PEEL Arrays are basically large PLAs that include logic macrocells with flop-flops and feedback to the logic planes. This structure is illustrated by Figure 16, which shows a programmable AND-plane that feeds a programmable OR-plane. The outputs of the OR-plane are divided into groups of four, and each group can be input to any of the logic cells. The logic cells provide registers for the sum terms and can feed-back the sum terms to the AND-plane. Also, the logic cells connect sum terms to I/O pins.

Because they have a PLA-like structure, logic capacity of PEEL Arrays is somewhat difficult to measure compared to the CPLDs discussed so far; an estimate is 1600 to 2800 equivalent gates.
PEEL Arrays offer relatively few I/O pins, with the largest part being offered in a 40 pin package. Since they do not comprise SPLD-like blocks, PEEL Arrays do not fit well into the CPLD category, however they are included here because they represent an example of PLA-based, rather than PAL-based devices, and they offer larger capacity than a typical SPLD.

The logic cell in the PEEL Arrays, depicted in Figure 17, includes a flip-flop, configurable as D, T, or JK, and two multiplexers. The multiplexers each produce an output of the logic cell and can provide either a registered or combinational output. One of the logic cell outputs can connect...
to an I/O pin and the other output is buried. One of the interesting features of the logic cell is that
the flip-flop clock, as well as preset and clear, are full sum-of-product logic functions. This differs
from all other CPLDs, which simply provide product terms for these signals and is attractive for
some applications. Because of their PLA-like OR-plane, the ICT PEEL Arrays are especially
well-suited to applications that require very wide sum terms.

2.2.8 Applications of CPLDs

We will now briefly examine the types of applications which best suit CPLD architectures.
Because they offer high speeds and a range of capacities, CPLDs are useful for a very wide assort-
ment of applications, from implementing random glue logic to prototyping small gate arrays. One
of the most common uses in industry at this time, and a strong reason for the large growth of the
CPLD market, is the conversion of designs that consist of multiple SPLDs into a smaller number
of CPLDs.

CPLDs can realize reasonably complex designs, such as graphics controller, LAN controllers,
UARTs, cache control, and many others. As a general rule-of-thumb, circuits that can exploit wide
AND/OR gates, and do not need a very large number of flip-flops are good candidates for imple-
mentation in CPLDs. A significant advantage of CPLDs is that they provide simple design
changes through re-programming (all commercial CPLD products are re-programmable). With in-
system programmable CPLDs it is even possible to re-configure hardware (an example might be
to change a protocol for a communications circuit) without power-down.

Designs often partition naturally into the SPLD-like blocks in a CPLD. The result is more pre-
dictable speed-performance than would be the case if a design were split into many small pieces
and then those pieces were mapped into different areas of the chip. Predictability of circuit imple-
mentation is one of the strongest advantages of CPLD architectures.
2.3 Commercially Available FPGAs

As one of the largest growing segments of the semiconductor industry, the FPGA market-place is volatile. As such, the pool of companies involved changes rapidly and it is somewhat difficult to say which products will be the most significant when the industry reaches a stable state. For this reason, and to provide a more focused discussion, we will not mention all of the FPGA manufacturers that currently exist, but will instead focus on those companies whose products are in widespread use at this time. In describing each device we will list its capacity, nominally in 2-input NAND gates as given by the vendor. Gate count is an especially contentious issue in the FPGA industry, and so the numbers given in this paper for all manufacturers should not be taken too seriously. Wags have taken to calling them “dog” gates, in reference to the traditional ratio between human and dog years.

There are two basic categories of FPGAs on the market today: 1. SRAM-based FPGAs and 2. antifuse-based FPGAs. In the first category, Xilinx and Altera are the leading manufacturers in terms of number of users, with the major competitor being AT&T. For antifuse-based products, Actel, Quicklogic and Cypress, and Xilinx offer competing products.

2.3.1 Xilinx SRAM-based FPGAs

The basic structure of Xilinx FPGAs is *array-based*, meaning that each chip comprises a two-dimensional array of logic blocks that can be interconnected via horizontal and vertical routing channels. An illustration of this type of architecture was shown in Figure 2. Xilinx introduced the first FPGA family, called the XC2000 series, in about 1985 and now offers three more generations: XC3000, XC4000, and XC5000. Although the XC3000 devices are still widely used, we will focus on the more recent and more popular XC4000 family. We note that XC5000 is similar to XC4000, but has been engineered to offer similar features at a more attractive price, with some penalty in speed. We should also note that Xilinx has recently introduced an FPGA family based
on anti-fuses, called the XC8100. The XC8100 has many interesting features, but since it is not yet in widespread use, we will not discuss it here. The Xilinx 4000 family devices range in capacity from about 2000 to more than 15,000 equivalent gates.

The XC4000 features a logic block (called a *Configurable Logic Block* (CLB) by Xilinx) that is based on look-up tables (LUTs). A LUT is a small one bit wide memory array, where the address lines for the memory are inputs of the logic block and the one bit output from the memory is the LUT output. A LUT with K inputs would then correspond to a $2^K \times 1$ bit memory, and can realize any logic function of its K inputs by programming the logic function’s truth table directly into the memory. The XC4000 CLB contains three separate LUTs, in the configuration shown in Figure 18. There are two 4-input LUTS that are fed by CLB inputs, and the third LUT can be used in combination with the other two. This arrangement allows the CLB to implement a wide range of logic functions of up to nine inputs, two separate functions of four inputs or other possibilities. Each CLB also contains two flip-flops.

![Figure 18 - Xilinx XC4000 Configurable Logic Block (CLB).](image-url)
Toward the goal of providing high density devices that support the integration of entire systems, the XC4000 chips have “system oriented” features. For instance, each CLB contains circuitry that allows it to efficiently perform arithmetic (i.e., a circuit that can implement a fast carry operation for adder-like circuits) and also the LUTs in a CLB can be configured as read/write RAM cells. A new version of this family, the 4000E, has the additional feature that the RAM can be configured as a dual port RAM with a single write and two read ports. In the 4000E, RAM blocks can be synchronous RAM. Also, each XC4000 chip includes very wide AND-planes around the periphery of the logic block array to facilitate implementing circuit blocks such as wide decoders.

Besides logic, the other key feature that characterizes an FPGA is its interconnect structure. The XC4000 interconnect is arranged in horizontal and vertical channels. Each channel contains some number of short wire segments that span a single CLB (the number of segments in each channel depends on the specific part number), longer segments that span two CLBs, and very long segments that span the entire length or width of the chip. Programmable switches are available (see Figure 5) to connect the inputs and outputs of the CLBs to the wire segments, or to connect one wire segment to another. A small section of a routing channel representative of an XC4000 device appears in Figure 19. The figure shows only the wire segments in a horizontal channel, and does not show the vertical routing channels, the CLB inputs and outputs, or the routing switches. An important point worth noting about the Xilinx interconnect is that signals must pass through switches to reach one CLB from another, and the total number of switches traversed depends on the particular set of wire segments used. Thus, speed-performance of an implemented circuit depends in part on how the wire segments are allocated to individual signals by CAD tools.
2.3.2 Altera FLEX 8000 and FLEX 10000 FPGAs

Altera’s FLEX 8000 series consists of a three-level hierarchy much like that found in CPLDs. However, the lowest level of the hierarchy consists of a set of lookup tables, rather than an SPLD-like block, and so the FLEX 8000 is categorized here as an FPGA. It should be noted, however, that FLEX 8000 is a combination of FPGA and CPLD technologies. FLEX 8000 is SRAM-based and features a four-input LUT as its basic logic block. Logic capacity ranges from about 4000 gates to more than 15,000 for the 8000 series.

The overall architecture of FLEX 8000 is illustrated in Figure 20. The basic logic block, called a Logic Element (LE) contains a four-input LUT, a flip-flop, and special-purpose carry circuitry for arithmetic circuits (similar to Xilinx XC4000). The LE also includes cascade circuitry that allows for efficient implementation of wide AND functions. Details of the LE are illustrated in Figure 21.

In the FLEX 8000, LEs are grouped into sets of 8, called Logic Array Blocks (LABs, a term borrowed from Altera’s CPLDs). As shown in Figure 22, each LAB contains local interconnect and each local wire can connect any LE to any other LE within the same LAB. Local interconnect...
Figure 20 - Architecture of Altera FLEX 8000 FPGAs.

Figure 21 - Altera FLEX 8000 Logic Element (LE).
also connects to the FLEX 8000’s global interconnect, called FastTrack. FastTrack is similar to Xilinx long lines in that each FastTrack wire extends the full width or height of the device. However, a major difference between FLEX 8000 and Xilinx chips is that FastTrack consists of only long lines. This makes the FLEX 8000 easy for CAD tools to automatically configure. All FastTrack wires horizontal wires are identical, and so interconnect delays in the FLEX 8000 are more predictable than FPGAs that employ many smaller length segments because there are fewer programmable switches in the longer paths. Predictability is furthered aided by the fact that connections between horizontal and vertical lines pass through active buffers.

The FLEX 8000 architecture has been extended in the state-of-the-art FLEX 10000 family. FLEX 10000 offers all of the features of FLEX 8000, with the addition of variable-sized blocks of SRAM, called Embedded Array Blocks (EABs). This idea is illustrated in Figure 23, which shows that each row in a FLEX 10000 chip has an EAB on one end. Each EAB is configurable to serve as an SRAM block with a variable aspect ratio: 256 x 8, 512 x 4, 1K x 2, or 2K x 1. In addition, an EAB can alternatively be configured to implement a complex logic circuit, such as a multiplier, by

![Figure 22 - Altera FLEX 8000 Logic Array Block (LAB).](image-url)
employing it as a large multi-output lookup table. Altera provides, as part of their CAD tools, several macro-functions that implement useful logic circuits in EABs. Counting the EABs as logic gates, FLEX 10000 offers the highest logic capacity of any FPGA, although it is hard to provide an accurate number.

2.3.3 AT&T ORCA FPGAs

AT&T’s SRAM-based FPGAs feature an overall structure similar to that in Xilinx FPGAs, and is called Optimized Reconfigurable Cell Array (ORCA). The ORCA logic block is based on LUTs, containing an array of *Programmable Function Units* (PFUs). The structure of a PFU is shown in Figure 24. A PFU possesses a unique kind of configurability among LUT-based logic blocks, in that it can be configured in the following ways: as four 4-input LUTs, as two 5-input LUTs, and as one 6-input LUT. A key element of this architecture is that when used as four 4-
input LUTs, several of the LUTs’ inputs must come from the same PFU input. While this reduces the apparent functionality of the PFU, it also significantly reduces the cost of the wiring associated with the chip. The PFU also includes arithmetic circuitry, like Xilinx XC4000 and Altera FLEX 8000, and like Xilinx XC4000 a PFU can be configured as a RAM block. A recently announced version of the ORCA chip also allows dual-port and synchronous RAM.

**Figure 24 - AT&T Programmable Function Unit (PFU).**

ORCA’s interconnect structure is also different from those in other SRAM-based FPGAs. Each PFU connects to interconnect that is configured in four-bit buses. This provides for more efficient support for “system-level” designs, since buses are common in such applications. The ORCA family has been extended in the ORCA 2 series, and offers very high logic capacity up to 40,000 logic gates. ORCA 2 features a two-level hierarchy of PFUs based on the original ORCA architecture.
2.3.4 Actel FPGAs

In contrast to FPGAs described above, the devices manufactured by Actel are based on anti-fuse technology. Actel offers three main families: Act 1, Act 2, and Act 3. Although all three generations have similar features, this paper will focus on the most recent devices, since they are apt to be more widely used in the longer term. Unlike the FPGAs described above, Actel devices are based on a structure similar to traditional gate arrays; the logic blocks are arranged in rows and there are horizontal routing channels between adjacent rows. This architecture is illustrated in Figure 25. The logic blocks in the Actel devices are relatively small in comparison to the LUT-based ones described above, and are based on multiplexers. Figure 26 illustrates the logic block in the Act 3 and shows that it comprises an AND and OR gate that are connected to a multiplexer-based circuit block. The multiplexer circuit is arranged such that, in combination with the two logic gates, a very wide range of functions can be realized in a single logic block. About half of the logic blocks in an Act 3 device also contain a flip-flop.

![Figure 25 - Structure of Actel FPGAs.](image-url)
As stated above, Actel’s interconnect is organized in horizontal routing channels. The channels consist of wire segments of various lengths with antifuses to connect logic blocks to wire segments or one wire to another. Also, although not shown in Figure 25, Actel chips have vertical wires that overlay the logic blocks, for signal paths that span multiple rows. In terms of speed-performance, it would seem probable that Actel chips are not fully predictable, because the number of antifuses traversed by a signal depends on how the wire segments are allocated during circuit implementation by CAD tools. However, Actel provides a rich selection of wire segments of different length in each channel and has developed algorithms that guarantee strict limits on the number of antifuses traversed by any two-point connection in a circuit which improves speed-performance significantly.

2.3.5 Quicklogic pASIC FPGAs

The main competitor for Actel in antifuse-based FPGAs is Quicklogic, whose has two families of devices, called pASIC and pASIC-2. The pASIC-2 is an enhanced version that has only recently been introduced, and will not be discussed here. The pASIC, as illustrated in Figure 27, has similarities to several other FPGAs: the overall structure is array-based like Xilinx FPGAs, its logic blocks use multiplexers similar to Actel FPGAs, and the interconnect consists of only long-
We note that the pASIC architecture is now independently developed by Cypress as well, but this discussion will focus only on Quicklogic’s version of their parts.

Quicklogic’s antifuse structure, called ViaLink, is illustrated on the left-hand side of Figure 27. It consists of a top layer of metal, an insulating layer of amorphous silicon, and a bottom layer of metal. When compared to Actel’s PLICE antifuse, ViaLink offers a very low on-resistance of about 50 ohms (PLICE is about 300 ohms) and a low parasitic capacitance. Figure 27 shows that ViaLink antifuses are present at every crossing of logic block pins and interconnect wires, providing generous connectivity. pASIC’s multiplexer-based logic block is depicted in Fig 28. It is more complex than Actel’s Logic Module, with more inputs and wide (6-input) AND-gates on the multiplexer select lines. Every logic block also contains a flip-flops.

Figure 27 - Structure of Quicklogic pASIC FPGA.
2.3.6 Applications of FPGAs

FPGAs have gained rapid acceptance and growth over the past decade because they can be applied to a very wide range of applications. A list of typical applications includes: random logic, integrating multiple SPLDs, device controllers, communication encoding and filtering, small to medium sized systems with SRAM blocks, and many more.

Other interesting applications of FPGAs are prototyping of designs later to be implemented in gate arrays, and also emulation of entire large hardware systems. The former of these applications might be possible using only a single large FPGA (which corresponds to a small Gate Array in terms of capacity), and the latter would entail many FPGAs connected by some sort of interconnect; for emulation of hardware, QuickTurn [Wolff90] (and others) has developed products that comprise many FPGAs and the necessary software to partition and map circuits.

Another promising area for FPGA application, which is only beginning to be developed, is the usage of FPGAs as custom computing machines. This involves using the programmable parts to “execute” software, rather than compiling the software for execution on a regular CPU. The

![Quicklogic (Cypress) Logic Cell.](image-url)
reader is referred to the FPGA-Based Custom Computing Workshop (FCCM) held for the last four years and published by the IEEE.

It was mentioned in Section 2.2.8 that when designs are mapped into CPLDs, pieces of the design often map naturally to the SPLD-like blocks. However, designs mapped into an FPGA are broken up into logic block-sized pieces and distributed through an area of the FPGA. Depending on the FPGA’s interconnect structure, there may be various delays associated with the interconnections between these logic blocks. Thus, FPGA performance often depends more upon how CAD tools map circuits into the chip than is the case for CPLDs.

3 Summary and Conclusions

We have presented a survey of field-programmable devices, describing the basic technology that provides the programmability and a description of many of the architectures in the current marketplace. This paper has not focussed on the equally important issue of CAD tools for FPDs.

We believe that over time programmable logic will become the dominant form of digital logic design and implementation. Their ease of access, principally through the low cost of the devices, makes them attractive to small firms and small parts of large companies. The fast manufacturing turn-around they provide is an essential element of success in the market. As architecture and CAD tools improve, the disadvantages of FPDs compared to Mask-Programmed Gate Arrays will lessen, and programmable devices will dominate.
4 Further Reading

A reasonable introduction to FPGAs can be found in the book:


A more specific discussion of three FPGA/CPLD architectures can be found in:


More detailed discussion of architectural trade-offs can be found in:


A textbook-like treatment, including digital logic design based on the Xilinx 3000 series and the Algotronix CAL chip can be found in:


Up to date research topics can be found in several conferences - CICC, ICCAD, DAC and the published proceedings: FPGA Symposium Series: FPGA ‘95: The 3rd Int’l ACM Symposium on Field-Programmable Gate Arrays, and FPGA ‘96. In addition, there have been international workshops on Field-Programmable Logic in Oxford (1991), Vienna (1992), Oxford (1993) Prague (1994), and Oxford (1995) and Darmstadt (1996), some of the proceedings of which are published by Abingdon Press, UK. Finally, there is the Canadian Workshop on Field Programmable Devices, 1994, 1995, and 1996.

5 References


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